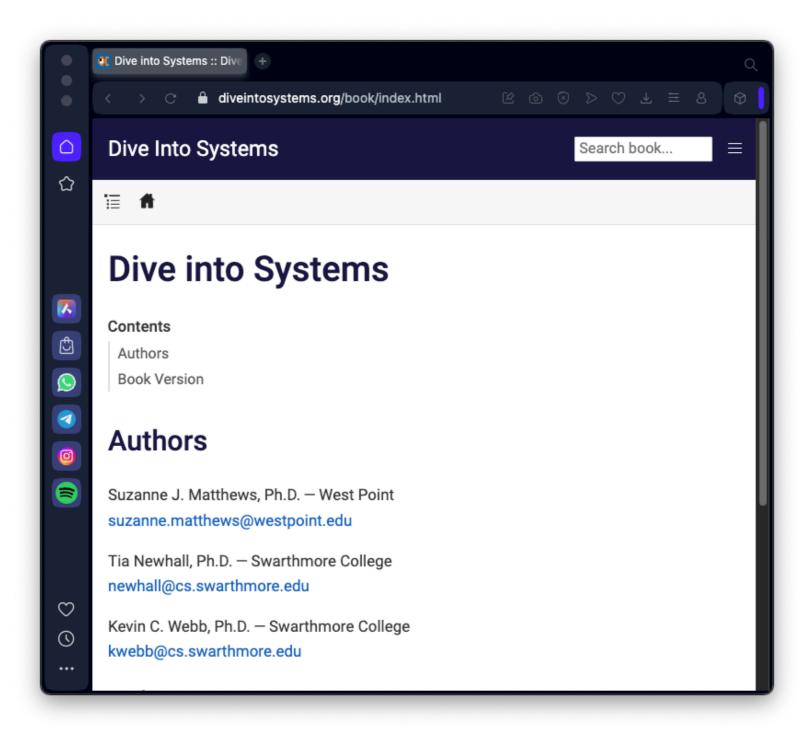
14a. Leveraging Shared Memory in the Multicore Era

For COMSC 142

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Free online textbook



https://diveintosystems.org/book/index.html

Topics

Ch 14a:

- 14.1. Programming Multicore Systems
- 14.2. POSIX Threads
- 14.3. Synchronizing Threads

Ch 14b:

- 14.4. Measuring Parallel Performance
- 14.5. Cache Coherence
- 14.6. Thread Safety
- 14.7. Implicit Threading with OpenMP

CPUs, Processors, and Cores

Processor

- any circuit that performs computation
- Central Processing Unit (CPU) is a processor

Multicore processor

processor with multiple compute cores

Core

a compute unit with an ALU, registers, and a bit of cache

Performance walls

Memory wall

- improvements in memory technology did not keep pace with improvements in clock speed
- memory is a bottleneck to performance
- speeding up the execution of a CPU no longer improves its overall system performance

Power wall

- increasing the number of transistors on a processor necessarily increases that processor's temperature and power consumption
- increases cost to power and cool the system
- power is now the dominant concern in computer system design

CPU v. GPU

- Graphics Processing Unit (GPU)
 - cores have even fewer transistors than CPU cores
 - are specialized for particular tasks involving vectors
 - A typical GPU can have 5,000 or more GPU cores
- Computing with GPUs is known as manycore computing
- In this chapter, we concentrate on multicore computing

```
$ 1scpu
Architecture: x86_64
CPU op-mode(s): 32-bit, 64-bit
Byte Order:
         Little Endian
CPU(s):
                  8
On-line CPU(s) list: 0-7
Thread(s) per core:
Core(s) per socket:
                  4
Socket(s):
Model name:
                  Intel(R) Core(TM) i7-3770 CPU @ 3.40GHz
CPU MHz:
                  1607.562
CPU max MHz: 3900.0000
CPU min MHz: 1600.0000
L1d cache:
                  32K
L1i cache: 32K
L2 cache:
                  256K
L3 cache:
                  8192K
```

Total # physical cores: sockets x cores per socket = 1 x 4

Hyperthreading

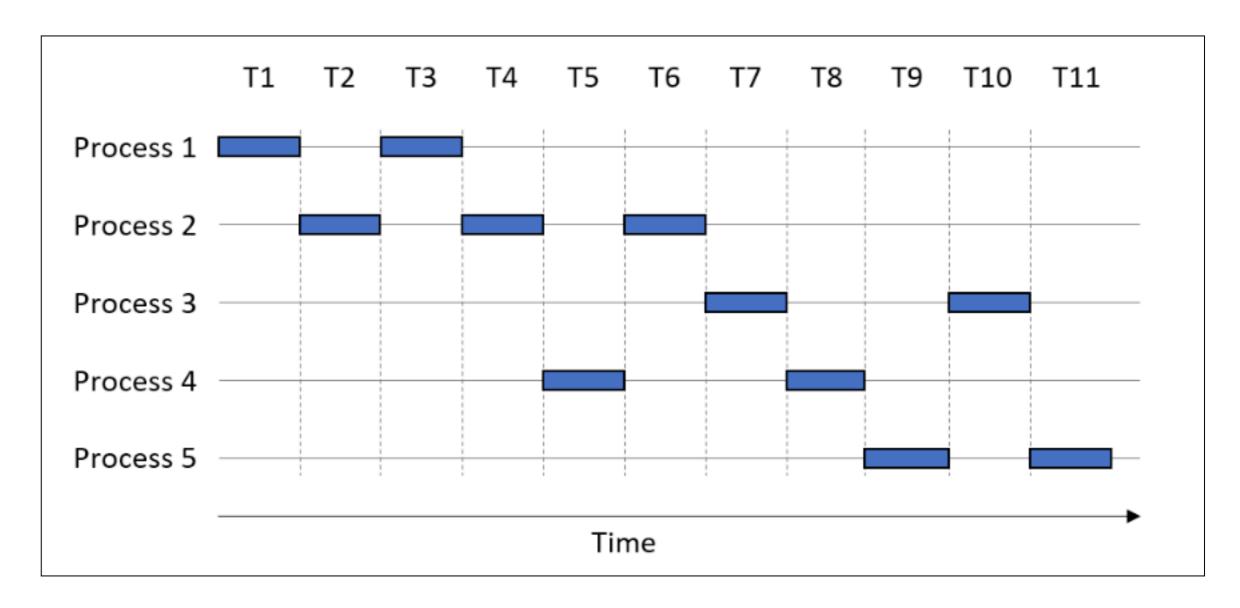
- Efficient processing of multiple threads on a single core
- So a processor that can run 2 threads per core
 - with 4 physical cores
 - has 8 logical cores
- Performance Cores and Efficiency Cores
 - E-cores consume less power
 - P-cores have higher clock speeds

14.1. Programming Multicore Systems

14.1.1. The Impact of Multicore Systems on Process Execution

Context switch

- occurs when the CPU changes which process it currently executes
- Diagram is for a single-core system



CPU Time and Wall-Clock Time

CPU time

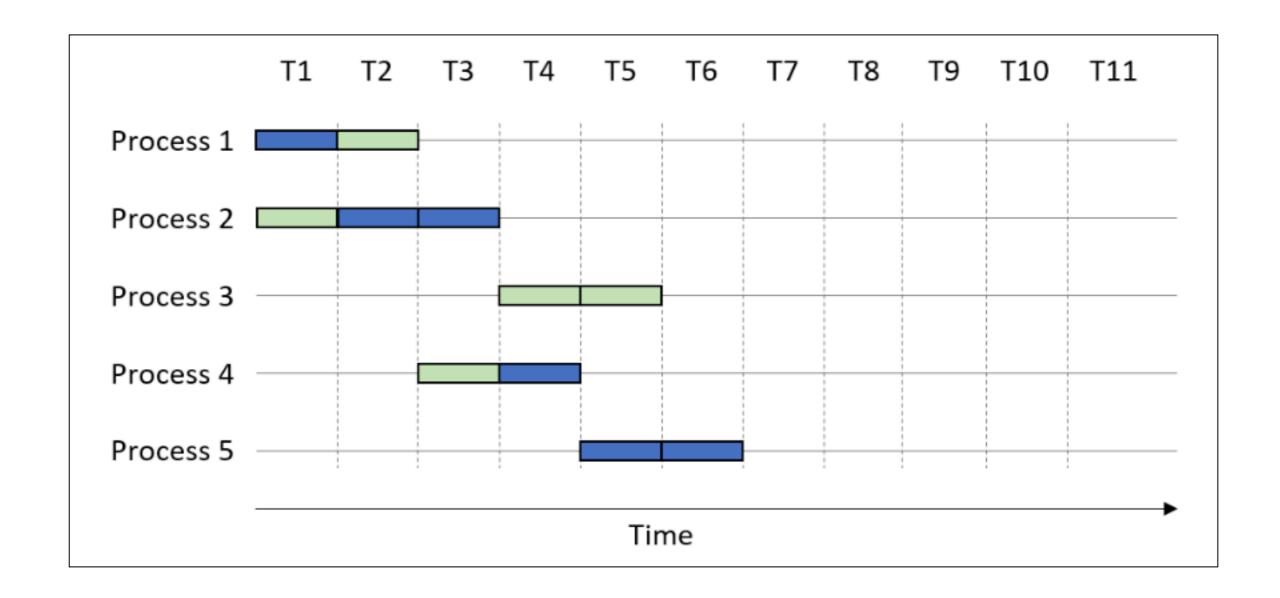
 measures the amount of time a process takes to execute on a CPU

Wall-clock time

- the amount of time a human perceives a process takes to complete.
- often significantly longer than the CPU time, due to context switches

Two-core system

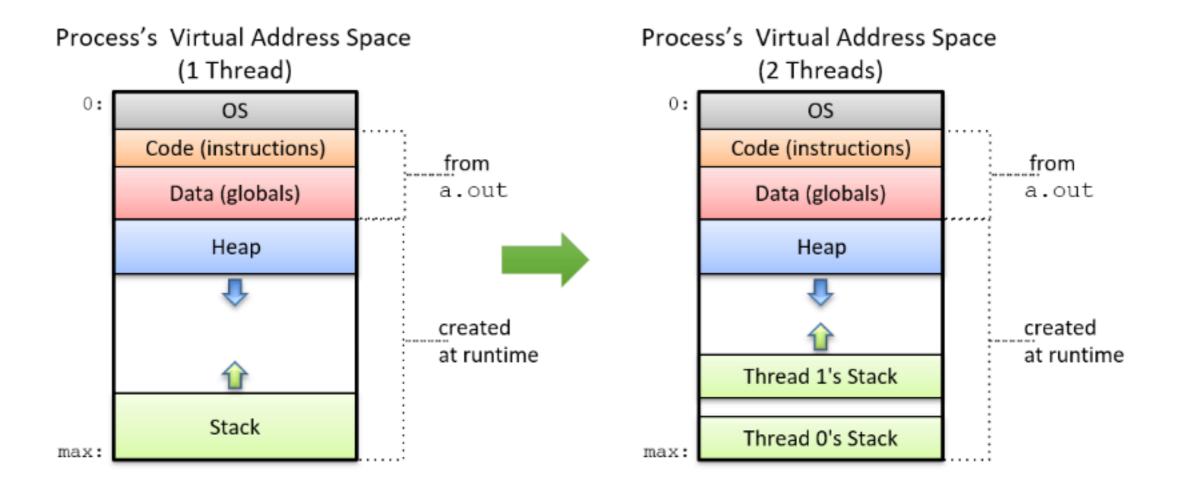
- CPU time is the same as single-core system
- But Wall Clock Time is decreased



14.1.2. Expediting Process Execution with Threads

Threads

• lightweight, independent execution flows

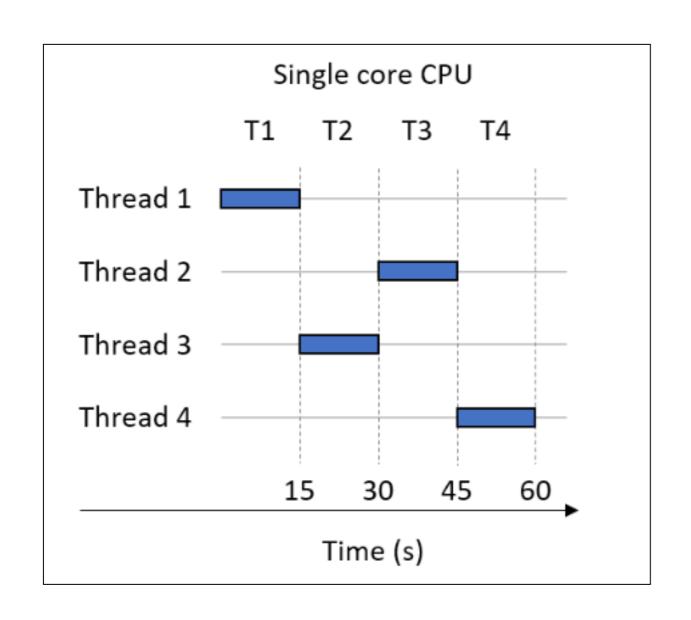


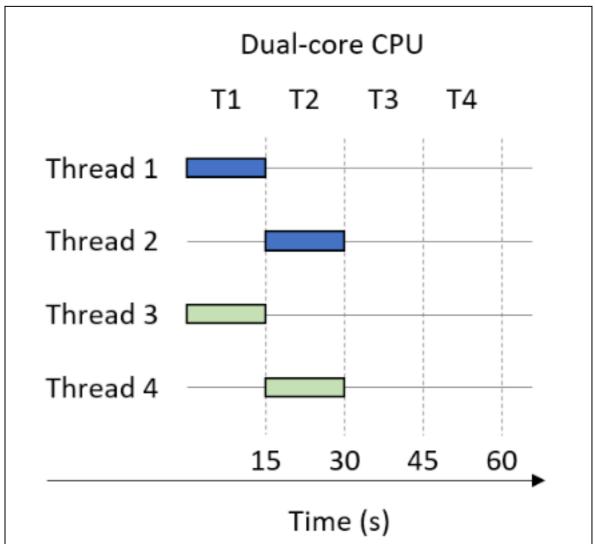
An Example: Scalar Multiplication

```
void scalar_multiply(int * array, long length, int s) {
   int i;
   for (i = 0; i < length; i++) {
      array[i] = array[i] * s;
   }
}</pre>
```

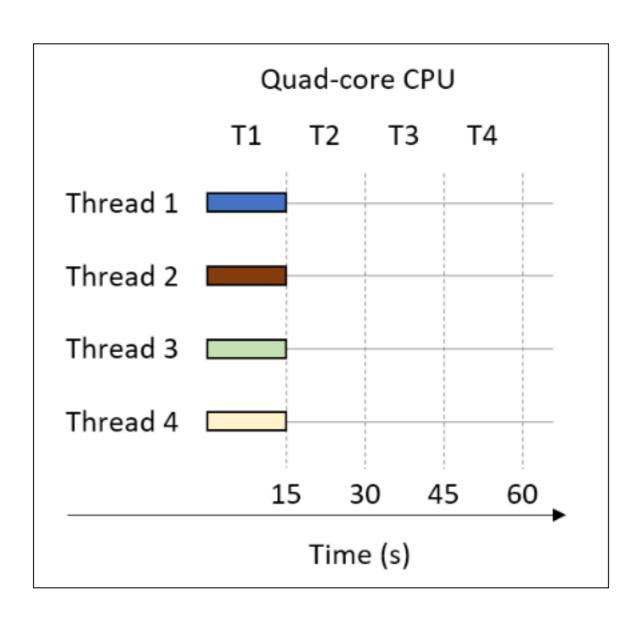
- Suppose that array has N total elements. To create a multithreaded version of this application with t threads, it is necessary to:
 - Create t threads.
 - Assign each thread a subset of the input array (i.e., N/t elements).
 - Instruct each thread to multiply the elements in its array subset by s

Four Threads





Four Threads



14.2. POSIX Threads

POSIX

- POSIX is an acronym for Portable Operating System Interface
- An IEEE standard that specifies how UNIX systems look, act, and feel
- Code using POSIX on a Linux machine will certainly work on other Linux machines, and it will likely work on machines running macOS or other UNIX variants

Hello Threading! Writing Your First Multithreaded Program

- wget https://samsclass.info/COMSC-142/proj/threads1.c
- gcc -o threads1 threads1.c
- #include <pthread.h>
- Define a thread function that we later pass to pthread_create
 - analogous to a main function
- The thread function is of type void *

```
sambowne - debian@debian: ~/COMSC-142/ch14 - ssh debian@192.168.121.173 - 80×17

| debian@debian: ~/COMSC-142/ch14$ cat threads1.c
| #include <stdio.h>
| #include <stdlib.h>
| #include <pthread.h>

/* The "thread function" passed to pthread_create. Each thread executes this | * function | and terminates | terturns | from this | function. | */
| void *HelloWorld(void *id) {
| /* We know the argument is a pointer to a long, so we cast it | from a | * generic (void *) to a (long *). | */
| long *myid = (long *) id;
| printf("Hello world! I | am thread %ld\n", *myid);
| return NULL; // We don't need our threads to return anything. | }
```

Hello Threading! Writing Your First Multithreaded Program

- main allocates space for thread_array and thread_ids
 - thread_array contains the set of addresses for each thread
 - thread_ids array stores the set of arguments that each thread is passed

```
sambowne - debian@debian: ~/COMSC-142/ch14 - ssh debian@192.168.121.173 - 80×18
int main(int argc, char **argv) {
    int i;
    int nthreads; //number of threads
    pthread_t *thread_array; //pointer to future thread array
    long *thread_ids;

// Read the number of threads to create from the command line.
    if (argc !=2) {
        fprintf(stderr, "usage: %s <n>\n", argv[0]);
        fprintf(stderr, "where <n> is the number of threads\n");
        return 1;
    }
    nthreads = strtol(argv[1], NULL, 10);

// Allocate space for thread structs and identifiers.
    thread_array = malloc(nthreads * sizeof(pthread_t));
    thread_ids = malloc(nthreads * sizeof(long));
```

Hello Threading! Writing Your First Multithreaded Program

- Creates threads with pthread_create
- Threads execute independently
- pthread_join waits for all the threads to complete
 - Terminates all the threads
 - Then proceeds as a single-thread process

```
sambowne — debian@debian: ~/COMSC-142/ch14 — ssh debian@192.168.121.173 — 80×18
// Assign each thread an ID and create all the threads.
for (i = 0; i < nthreads; i++) {
    thread ids[i] = i;
    pthread_create(&thread_array[i], NULL, HelloWorld, &thread_ids[i]);
/* Join all the threads. Main will pause in this loop until all threads
* have returned from the thread function. */
for (i = 0; i < nthreads; i++) {
    pthread_join(thread_array[i], NULL);
free(thread array);
free(thread_ids);
return 0;
```

Thread order

 Threads may not execute in order

```
sambowne — debian@debianarm: ~/COMSC-142/ch14 — ssh debian@172....
debian@debianarm:~/COMSC-142/ch14$ ./threads1 10
Hello world! I am thread 0
Hello world! I am thread 1
Hello world! I am thread 2
Hello world! I am thread 3
Hello world! I am thread 4
Hello world! I am thread 5
Hello world! I am thread 7
Hello world! I am thread 6
Hello world! I am thread 9
Hello world! I am thread 8
debian@debianarm:~/COMSC-142/ch14$ ./threads1 10
Hello world! I am thread 1
Hello world! I am thread 0
Hello world! I am thread 5
Hello world! I am thread 2
Hello world! I am thread 3
Hello world! I am thread 8
Hello world! I am thread 4
Hello world! I am thread 9
Hello world! I am thread 6
Hello world! I am thread 7
debian@debianarm:~/COMSC-142/ch14$ sdsfswfw
```

14.2.4. Revisiting Scalar Multiplication

- wget https://samsclass.info/COMSC-142/proj/threads2.c
- gcc -o threads2 threads2.c

```
debian@debianarm:~/COMSC-142/ch14$ cat threads2.c

#include <stdio.h>
#include <pthread.h>

#define LENGTH 1000000000

long *array; // defined in main
long length = LENGTH;
long nthreads; //number of threads
long s = 10; //scalar
```

```
sambowne — debian@debianarm: ~/COMSC-142/ch14 — ssh debian@172.16.71.132 — 76×22
void *scalar_multiply(void *id) {
    long *myid = (long *) id;
    int i;
    //assign each thread its own chunk of elements to process
    long chunk = length / nthreads;
    long start = *myid * chunk;
    long end = start + chunk;
    if (*myid == nthreads - 1) {
        end = length;
    }
    //perform scalar multiplication on assigned chunk
    for (i = start; i < end; i++) {
        array[i] *= s;
    }
    // printf("Thread %d done\n", *myid);
    return NULL;
```

```
• • •
            sambowne — debian@debianarm: ~/COMSC-142/ch14 — ssh debian@172.16.71.132 — 84×21
int main(int argc, char **argv) {
    int i;
    // int nthreads; //number of threads
    pthread_t *thread_array; //pointer to future thread array
    long *thread_ids;
    array = malloc(LENGTH * sizeof(long));
    // Read the number of threads to create from the command line.
    if (argc !=2) {
        fprintf(stderr, "usage: %s <n>\n", argv[0]);
        fprintf(stderr, "where <n> is the number of threads\n");
        return 1;
    nthreads = strtol(argv[1], NULL, 10);
    // Allocate space for thread structs and identifiers.
    thread_array = malloc(nthreads * sizeof(pthread_t));
    thread_ids = malloc(nthreads * sizeof(long));
```

```
sambowne — debian@debianarm: ~/COMSC-142/ch14 — ssh debian@172.16.71.132 — 82×18
// Assign each thread an ID and create all the threads.
for (i = 0; i < nthreads; i++) {
    thread_ids[i] = i;
    pthread_create(&thread_array[i], NULL, scalar_multiply, &thread_ids[i]);
/* Join all the threads. Main will pause in this loop until all threads
 * have returned from the thread function. */
for (i = 0; i < nthreads; i++) {
    pthread_join(thread_array[i], NULL);
free(thread_array);
free(thread_ids);
return 0;
```

My virtual system has 4 CPUs

```
debian@debianarm:~/COMSC-142/ch14$ { time(./threads2 1) 2>&1; } | grep real real 0m2.055s
debian@debianarm:~/COMSC-142/ch14$ { time(./threads2 2) 2>&1; } | grep real real 0m1.181s
debian@debianarm:~/COMSC-142/ch14$ { time(./threads2 2) 2>&1; } | grep real real 0m0.786s
debian@debianarm:~/COMSC-142/ch14$ { time(./threads2 4) 2>&1; } | grep real real 0m0.786s
debian@debianarm:~/COMSC-142/ch14$ { time(./threads2 8) 2>&1; } | grep real real 0m0.788s
debian@debianarm:~/COMSC-142/ch14$
```

```
    sambowne — debian@debianarm: ~/COMSC-142/ch14 — ssh debian@172.1...

debian@debianarm:~/COMSC-142/ch14$ lscpu
Architecture:
                           aarch64
  CPU op-mode(s):
                           64-bit
  Byte Order:
                           Little Endian
CPU(s):
  On-line CPU(s) list:
                           0 - 3
Vendor ID:
                           Apple
  Model name:
    Model:
                           0
    Thread(s) per core:
                           1
    Core(s) per socket:
                           4
    Socket(s):
                           1
```

14.2.5. Improving Scalar Multiplication: Multiple Arguments

To avoid global variables, define a struct

```
struct t_arg {
   int *array; // pointer to shared array
   long length; // num elements in array
   long s; //scaling factor
   long numthreads; // total number of threads
   long id; // logical thread id
};
```

In main()

```
long nthreads = strtol(argv[1], NULL, 10); //get number of threads
long length = strtol(argv[2], NULL, 10); //get length of array
long s = strtol( argv[3], NULL, 10 ); //get scaling factor
int *array = malloc(length*sizeof(int));
//allocate space for thread structs and identifiers
pthread_t *thread_array = malloc(nthreads * sizeof(pthread_t));
struct t_arg *thread_args = malloc(nthreads * sizeof(struct t_arg));
//Populate thread arguments for all the threads
for (i = 0; i < nthreads; i++){}
    thread_args[i].array = array;
    thread_args[i].length = length;
    thread_args[i].s = s;
    thread_args[i].numthreads = nthreads;
    thread_args[i].id = i;
```

Pass struct as argument

In main()

```
for (i = 0; i < nthreads; i++){
    pthread_create(&thread_array[i], NULL, scalar_multiply, &thread_args[i]);
}</pre>
```



Ch 14a-1

14.3. Synchronizing Threads

14.3. Synchronizing Threads

- Thread synchronization
 - Forcing threads to execute in a particular order
 - May slow execution, but may be necessary
- Four methods:
 - Mutex
 - Semaphores
 - Barriers
 - Condition variables
- All threads of a multithreaded process share the same heap

CountSort

- Input is an array of N elements, with only R possible values
 - R is much smaller than N
- Input is an array A of 15 items:
 - A = [9, 0, 2, 7, 9, 0, 1, 4, 2, 2, 4, 5, 0, 9, 1]
 - Possible values are 0 through 9
- CountSort counts the number of times each value occurs
- Creates an array of counts
 - counts = [3, 2, 3, 0, 2, 1, 0, 1, 0, 3]
- Use those counts to build a sorted array
 - A = [0, 0, 0, 1, 1, 2, 2, 2, 4, 4, 5, 7, 9, 9, 9]

CountSort

- wget https://samsclass.info/COMSC-142/proj/countSort.c
- gcc -o countSort countSort.c

```
    sambowne — debian@debianarm: ~/COMSC-142/ch14 — ssh debian@1...

debian@debianarm: ~/COMSC-142/ch14$ ./countSort 15 1

array before sort:
5 8 8 5 8 7 5 1 7 7 3 3 8 3 4

result after sort:
1 3 3 3 4 5 5 5 7 7 7 8 8 8 8

debian@debianarm: ~/COMSC-142/ch14$
```

```
/*step 1:
    * compute the frequency of all the elements in the input array and store
    * the associated counts of each element in array counts. The elements in the
    * counts array are initialized to zero prior to the call to this function.
    */
void countElems(int *counts, int *array_A, long length) {
    int val, i;
    for (i = 0; i < length; i++) {
        val = array_A[i]; //read the value at index i
        counts[val] = counts[val] + 1; //update corresponding location in counts
}
</pre>
```

```
sambowne — debian@debianarm: ~/COMSC-142/ch14 — ssh debian@172.16.71.132 — 84×17
/* step 2:
* overwrite the input array (array_A) using the frequencies stored in the
   array counts
*/
void writeArray(int *counts, int *array_A) {
    int i, j = 0, amt;
    for (i = 0; i < MAX; i++) { //iterate over the counts array
        amt = counts[i]; //capture frequency of element i
        while (amt > 0) { //while all values aren't written
            array_A[j] = i; //replace value at index j of array_A with i
            j++; //go to next position in array_A
            amt--; //decrease the amount written by 1
```

Parallel countElems

```
/*parallel version of step 1 (first cut) of CountSort algorithm:
    * extracts arguments from args value
    * calculates the portion of the array that thread is responsible for counting
    * computes the frequency of all the elements in assigned component and stores
    * the associated counts of each element in counts array

*/

void *countElems( void *args ) {
    struct t_arg * myargs = (struct t_arg *)args;
    //extract arguments (omitted for brevity)
    int *array = myargs->ap;
    long *counts = myargs->countp;
    //... (get nthreads, length, myid)
```

Parallel countless

```
//assign work to the thread
long chunk = length / nthreads; //nominal chunk size
long start = myid * chunk;
long end = (myid + 1) * chunk;
long val;
if (myid == nthreads-1) {
    end = length;
}
long i;
//heart of the program
for (i = start; i < end; i++) {</pre>
   val = array[i];
    counts[val] = counts[val] + 1;
}
return NULL;
```

Results

- Error: different results for different number of threads
- More threads cause undercounts

```
$ gcc -o countElems_p countElems_p.c -pthread
$./countElems_p 10000000 1 1
Counts array:
999170 1001044 999908 1000431 999998 1001479 999709 997250 1000804 1000207
$./countElems_p 10000000 1 2
Counts array:
661756 661977 657828 658479 657913 659308 658561 656879 658070 657276
$./countElems_p 10000000 1 4
Counts array:
579846 580814 580122 579772 582509 582713 582518 580917 581963 581094
```

Data race (race condition)

- Single-threaded version
 - counts[val] = counts[val] + 1
- Multithreaded version
 - 1. Read **counts[val]** and place into a **register**.
 - 2. Modify the **register** by incrementing it by one.
 - 3. Write the contents of the register to counts[val].

Two threads

Time	Thread 0	Thread 1
i	Read counts[1] and place into Core 0's register	•••
i+1	Increment register by 1	Read counts[1] and place into Core 1's register
i+2	Overwrite counts[1] with con- tents of register	Increment register by 1
i+3		Overwrite counts[1] with con-

Atomic operations

- An atomic operation is "all or none"
 - It either completes correctly, or fails completely
- We must isolate the critical section of code
 - And make it execute atomically

```
long i;
for (i = start; i < end; i++) {
   val = array[i];
   counts[val] = counts[val] + 1; //this line needs to be protected
}</pre>
```

Sequence without error

Time	Thread 0	Thread 1
i	Read counts[1] and place into Core 0's register	
i+1	Increment register by 1	•••
i+2	Overwrite counts[1] with con- tents of register	
i+3	•••	Read counts[1] and place into Core 1's register
i+4	***	Increment register by 1
i+5		Overwrite counts[1] with con- tents of register

Using a Mutex

Define the mutex as a global variable

```
pthread_mutex_t mutex; //global declaration of mutex, initialized in main()
```

- In countElem, only one thread at a time can get a lock on the mutex
 - Mutexes are unlocked by default

```
//heart of the program
pthread_mutex_lock(&mutex); //acquire the mutex lock
for (i = start; i < end; i++) {
   val = array[i];
   counts[val] = counts[val] + 1;
}
pthread_mutex_unlock(&mutex); //release the mutex lock</pre>
```

Creating and destroying the mutex

```
//code snippet from main():

pthread_mutex_init(&mutex, NULL); //initialize the mutex

for (t = 0; t < nthreads; t++) {
    pthread_create( &thread_array[t], NULL, countElems, &thread_args[t] );
}

for (t = 0; t < nthreads; t++) {
    pthread_join(thread_array[t], NULL);
}

pthread_mutex_destroy(&mutex); //destroy (free) the mutex</pre>
```

Counting is correct now

```
$ ./countElems_p_v2 10000000 1 1
Counts array:
999170 1001044 999908 1000431 999998 1001479 999709 997250 1000804 1000207
$ ./countElems_p_v2 10000000 1 2
Counts array:
999170 1001044 999908 1000431 999998 1001479 999709 997250 1000804 1000207
$ ./countElems_p_v2 10000000 1 4
Counts array:
999170 1001044 999908 1000431 999998 1001479 999709 997250 1000804 1000207
```

Measuring performance

More threads consume more time!

```
$ ./countElems_p_v2 100000000 0 1
Time for Step 1 is 0.368126 s

$ ./countElems_p_v2 100000000 0 2
Time for Step 1 is 0.438357 s

$ ./countElems_p_v2 100000000 0 4
Time for Step 1 is 0.519913 s
```

Locked for whole loop

- One thread must complete its loop before another thread can run
- Makes the program effectively serial

```
//code snippet from the countElems function from earlier
//the heart of the program
pthread_mutex_lock(&mutex); //acquire the mutex lock
for (i = start; i < end; i++){
   val = array[i];
   counts[val] = counts[val] + 1;
}
pthread_mutex_unlock(&mutex); //release the mutex lock</pre>
```

The Mutex: Reloaded

Only lock for each write operation

```
/*modified code snippet of countElems function:
  *locks are now placed INSIDE the for loop!

*/
//the heart of the program
for (i = start; i < end; i++) {
    val = array[i];
    pthread_mutex_lock(&m); //acquire the mutex lock
    counts[val] = counts[val] + 1;
    pthread_mutex_unlock(&m); //release the mutex lock
}</pre>
```

Operates correctly

```
$ ./countElems_p_v3 10000000 1 1
Counts array:
999170 1001044 999908 1000431 999998 1001479 999709 997250 1000804 1000207
$ ./countElems_p_v3 10000000 1 2
Counts array:
999170 1001044 999908 1000431 999998 1001479 999709 997250 1000804 1000207
$ ./countElems_p_v3 10000000 1 4
Counts array:
999170 1001044 999908 1000431 999998 1001479 999709 997250 1000804 1000207
```

Performance

- Locking and unlocking are expensive operations
 - A lot of time overhead

```
$ ./countElems_p_v3 100000000 0 1
Time for Step 1 is 1.92225 s

$ ./countElems_p_v3 100000000 0 2
Time for Step 1 is 10.9704 s

$ ./countElems_p_v3 100000000 0 4
Time for Step 1 is 9.13662 s
```

The Mutex: Revisited

- Each thread has a private local array of counts
- Only uses mutex when adding totals to global counts array

```
//heart of the program
for (i = start; i < end; i++) {</pre>
   val = array[i];
    //updates local counts array
    local_counts[val] = local_counts[val] + 1;
//update to global counts array
pthread_mutex_lock(&mutex); //acquire the mutex lock
for (i = 0; i < MAX; i++) {
    counts[i] += local_counts[i];
pthread_mutex_unlock(&mutex); //release the mutex lock
```

Performance

More threads consume less wall time

```
$ ./countElems_p_v3 100000000 0 1
Time for Step 1 is 0.334574 s

$ ./countElems_p_v3 100000000 0 2
Time for Step 1 is 0.209347 s

$ ./countElems_p_v3 100000000 0 4
Time for Step 1 is 0.130745 s
```

Deadlock

 A deadlocked thread is blocked from execution by another thread, which itself is blocked on a blocked thread

```
struct account {
    pthread_mutex_t lock;
    int balance;
};
```

```
void *Transfer(void *args){
    //argument passing removed to increase readability
    //...
    pthread_mutex_lock(&fromAcct->lock);
    pthread_mutex_lock(&toAcct->lock);
    fromAcct->balance -= amt;
    toAcct->balance += amt;
    pthread_mutex_unlock(&fromAcct->lock);
    pthread_mutex_unlock(&toAcct->lock);
    return NULL;
```

Deadlock Condition

- Thread 0 sends funds from A to B
- Thread 1 sends funds from B to A

```
Thread 0
Transfer(...) {
    //acctA is fromAcct
    //acctB is toAcct
    pthread_mutex_lock(&acctA->lock);
        Thread 1 gets here
    pthread_mutex_lock(&acctB->lock);
        Figure 1. An example of deadlock
Thread 1
Thread 1

Thread 1

Thread 1

Thread 1

Thread 1

Thread 1

Thread 1

Thread 1

Thread 2

Thread 3

Thread 4

Thread 5

Thread 6

Thread 6

Thread 7

Thread 6

Thread 1

Thread 6

Thread 6

Thread 7

Thread 7

Thread 7

Thread 6

Thread 7

Thread 7

Thread 6

Thread 7

Thread 7

Thread 7

Thread 6

Thread 7

Thread 7

Thread 7

Thread 9

Thread 9</
```

Avoiding deadlock

Only lock one mutex at a time

```
void *Transfer(void *args){
    //argument passing removed to increase readability
    //...
    pthread_mutex_lock(&fromAcct->lock);
    fromAcct->balance -= amt;
    pthread_mutex_unlock(&fromAcct->lock);
    pthread_mutex_lock(&toAcct->lock);
    toAcct->balance += amt;
    pthread_mutex_unlock(&toAcct->lock);
    return NULL;
```

14.3.2. Semaphores

- Can have many values
- Counting semaphore
 - Values: 0 through r
 - Decrements each time a resource is uses
 - When the counting semaphore reaches 0, no more resources are available
 - Any other threads trying to acquire the resource are blocked
- Can be locked by default
- Any thread can unlock a semaphore
 - Only the calling thread can unlock a mutex

Using semaphores

- #include <semaphore.h>
- There is no standard; function calls are different on different systems
- Declaration: sem_t semaphore
- Initialize: sem_init(&semaphore, 1, 0)
 - Parameters: address of semaphore, default state, whether to share with threads of a process (e.g., with value 0) or between processes (e.g., with value 1)
- Destroy: sem_destroy(&semaphore)

Using semaphores

- sem_wait function indicates that a resource is being used, and decrements the semaphore
 - Blocks if semaphore reaches zero
- sem_post indicates that a resource is being freed, and increments the semaphore

14.3.3. Other Synchronization Constructs

barrier

- part of the pthreads library
- forces all threads to reach a common point in execution before releasing the threads to continue executing

• Usage:

- Declare a global variable pthread_barrier_t barrier
- Initialize in main pthread_barrier_init(&barrier)
- Destroy after use pthread_barrier_destroy(&barrier)
- pthread_barrier_wait function creates a synchronization point

Barrier example

```
void *threadEx(void *args){
    //parse args
    //...
    long myid = myargs->id;
    int nthreads = myargs->numthreads;
    int *array = myargs->array
    printf("Thread %ld starting thread work!\n", myid);
    pthread_barrier_wait(&barrier); //forced synchronization point
    printf("All threads have reached the barrier!\n");
    for (i = start; i < end; i++) {</pre>
        array[i] = array[i] * 2;
    printf("Thread %ld done with work!\n", myid);
    return NULL;
```

Condition Variables

- part of the **pthreads** library
- force a thread to block until a particular condition is reached
- always used in conjunction with a mutex

Condition variables

- Usage:
 - initialize with pthread_cond_init
 - destroy with pthread_cond_destroy
 - pthread_cond_wait(&cond, &mutex)
 - causes the calling thread to block on the condition variable cond until another thread signals it (or "wakes" it up)
 - pthread_cond_signal(&cond)
 - causes the calling thread to unblock (or signal) another thread that is waiting

main()

```
// create some chicken and farmer threads
for (i = 0; i < (2 * nthreads); i++) {
    if ( (i % 2) == 0 ) {
        ret = pthread_create(&thread_array[i], NULL,
                             chicken, &thread_args[i]);
    else {
        ret = pthread_create(&thread_array[i], NULL,
                             farmer, &thread_args[i] );
```

main()

```
// wait for chicken and farmer threads to exit
for (i = 0; i < (2 * nthreads); i++) {
    ret = pthread_join(thread_array[i], NULL);
// clean-up program state
pthread_mutex_destroy(&mutex); //destroy the mutex
pthread_cond_destroy(&eggs); //destroy the cond var
return 0;
```

```
void *chicken(void *args ) {
    struct t_arg *myargs = (struct t_arg *)args;
    int *num_eggs, i, num;
    num_eggs = myargs->num_eggs;
    i = 0;
    // lay some eggs
    for (i = 0; i < myargs->total_eggs; i++) {
        usleep(EGGTIME); //chicken sleeps
        pthread_mutex_lock(myargs->mutex);
        *num_eggs = *num_eggs + 1; // update number of eggs
        num = *num_eggs;
        pthread_cond_signal(myargs->eggs); // wake a sleeping farmer (squawk)
        pthread_mutex_unlock(myargs->mutex);
        printf("chicken %d created egg %d available %d\n", myargs->id, i, num);
    return NULL;
```

```
void *farmer(void *args ) {
    struct t_arg * myargs = (struct t_arg *)args;
    int *num_eggs, i, num;
    num_eggs = myargs->num_eggs;
    i = 0:
    for (i = 0; i < myargs->total_eggs; i++) {
        pthread_mutex_lock(myargs->mutex);
        while (*num_eggs == 0 ) { // no eggs to collect
            // wait for a chicken to lay an egg
            pthread_cond_wait(myargs->eggs, myargs->mutex);
        }
        // we hold mutex lock here and num_eggs > 0
        num = *num_eggs;
        *num_eggs = *num_eggs - 1;
        pthread_mutex_unlock(myargs->mutex);
        printf("farmer %d gathered egg %d available %d\n", myargs->id, i, num);
    return NULL;
```

Broadcasting

- pthread_cond_broadcast(&cond)
 - wakes up all threads that are blocked on condition cond

```
// start barrier code
pthread_mutex_lock(&mutex);
*n_reached++;
printf("Thread %ld starting work!\n", myid)
// if some threads have not reached the barrier
while (*n_reached < nthreads) {</pre>
    pthread_cond_wait(&barrier, &mutex);
// all threads have reached the barrier
printf("all threads have reached the barrier!\n");
pthread_cond_broadcast(&barrier);
pthread_mutex_unlock(&mutex);
// end barrier code
```



Ch 14a-2